

Četvrto predavanje (1. travnja 2022.)

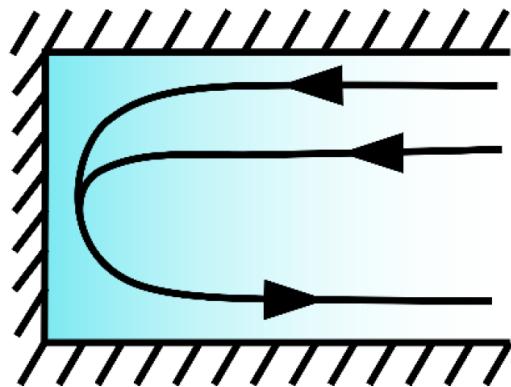
M. Orlić: Predavanja iz Dinamike obalnog mora

2. Vjetrovno strujanje u okrajnjim morima

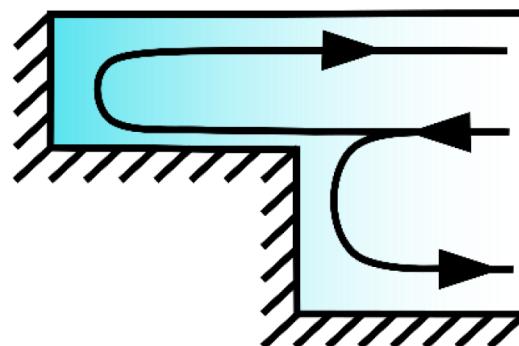
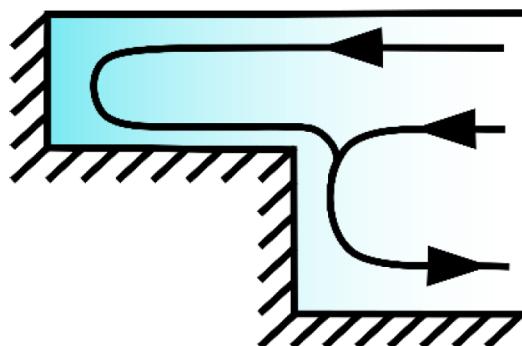
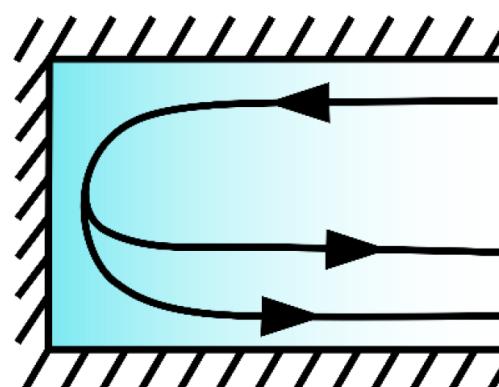
2.1. Uvod

Jadran – shematski prikaz rezidualne cirkulacije

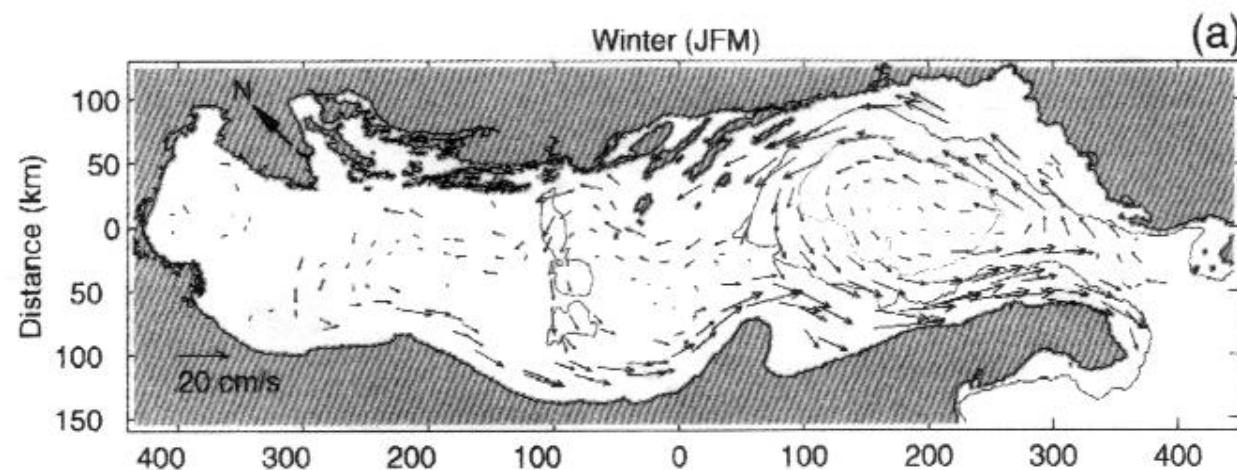
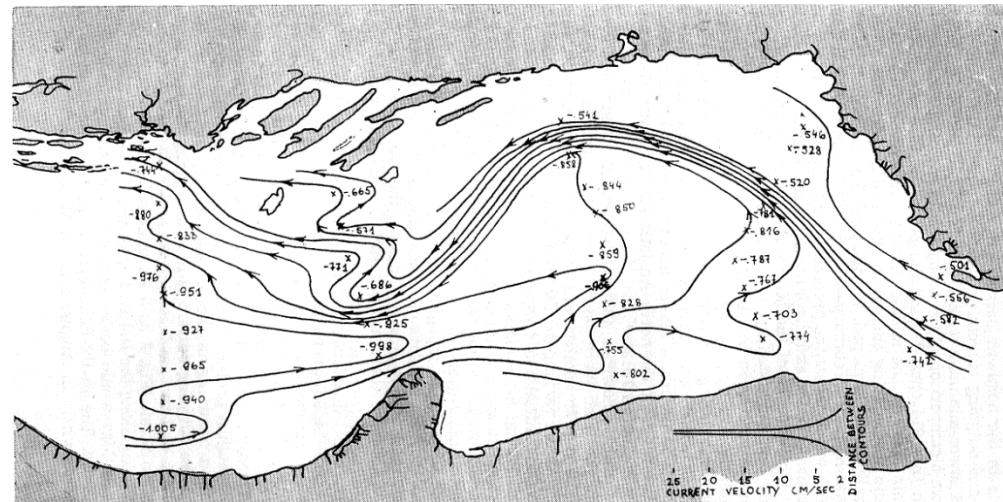
ZIMA



LJETO

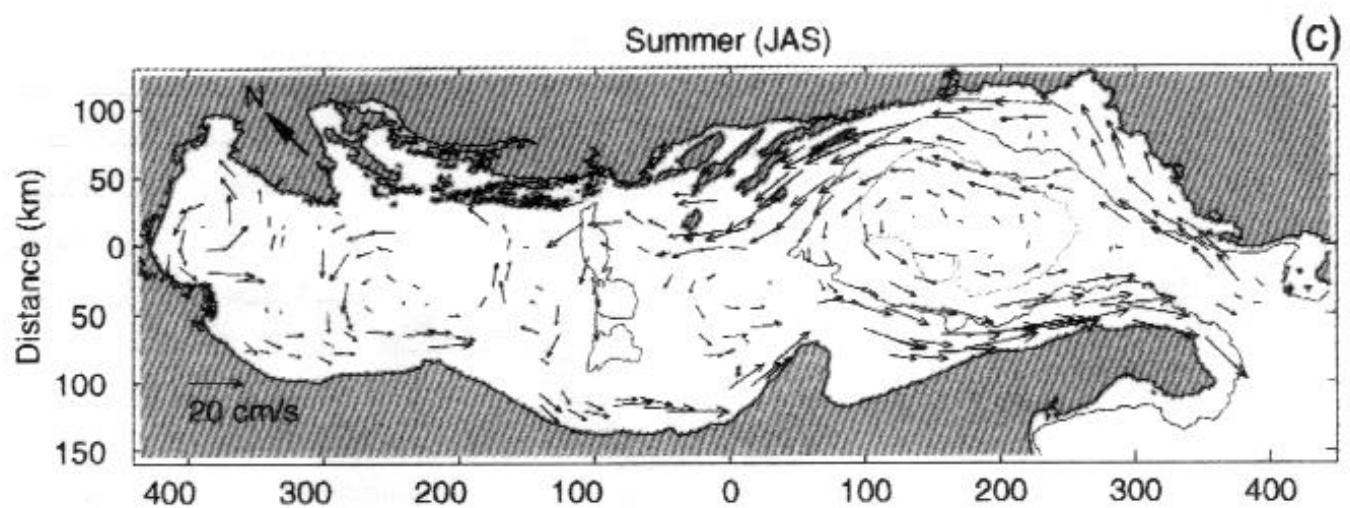
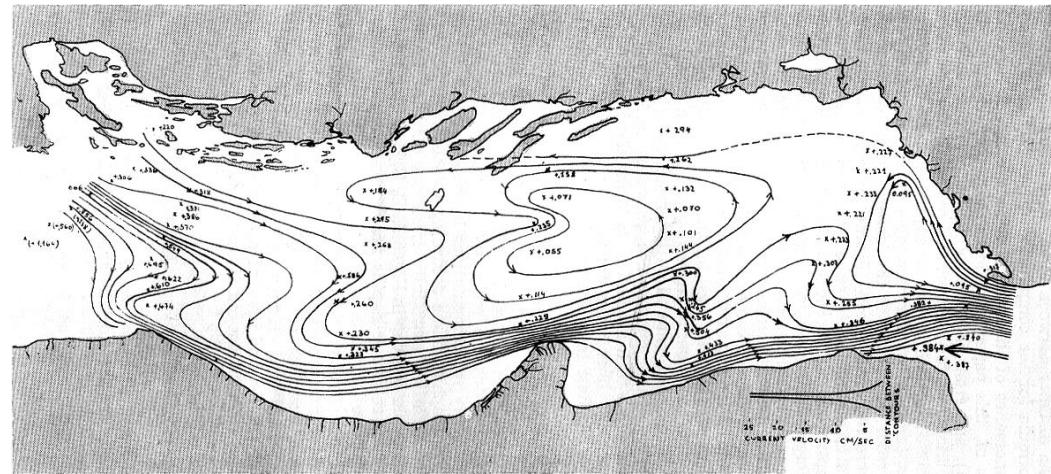


Jadran – zima



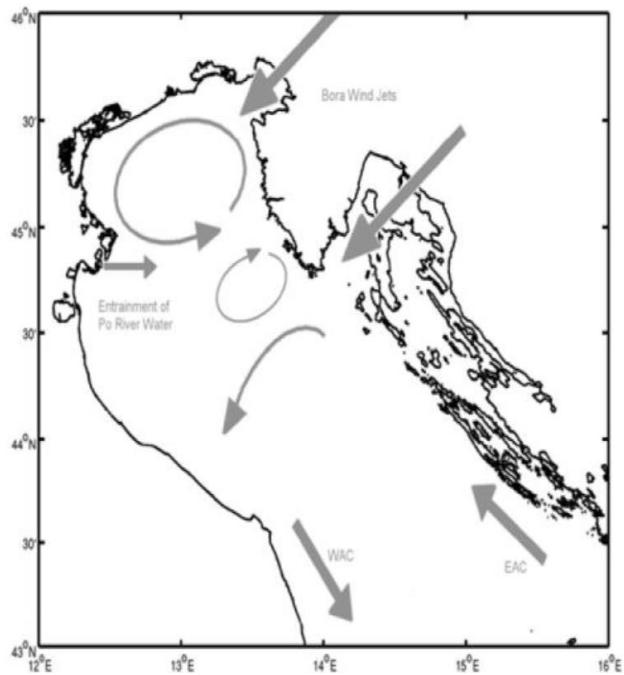
Zore, 1956.
Poulain, 2001.

Jadran – Ijeto



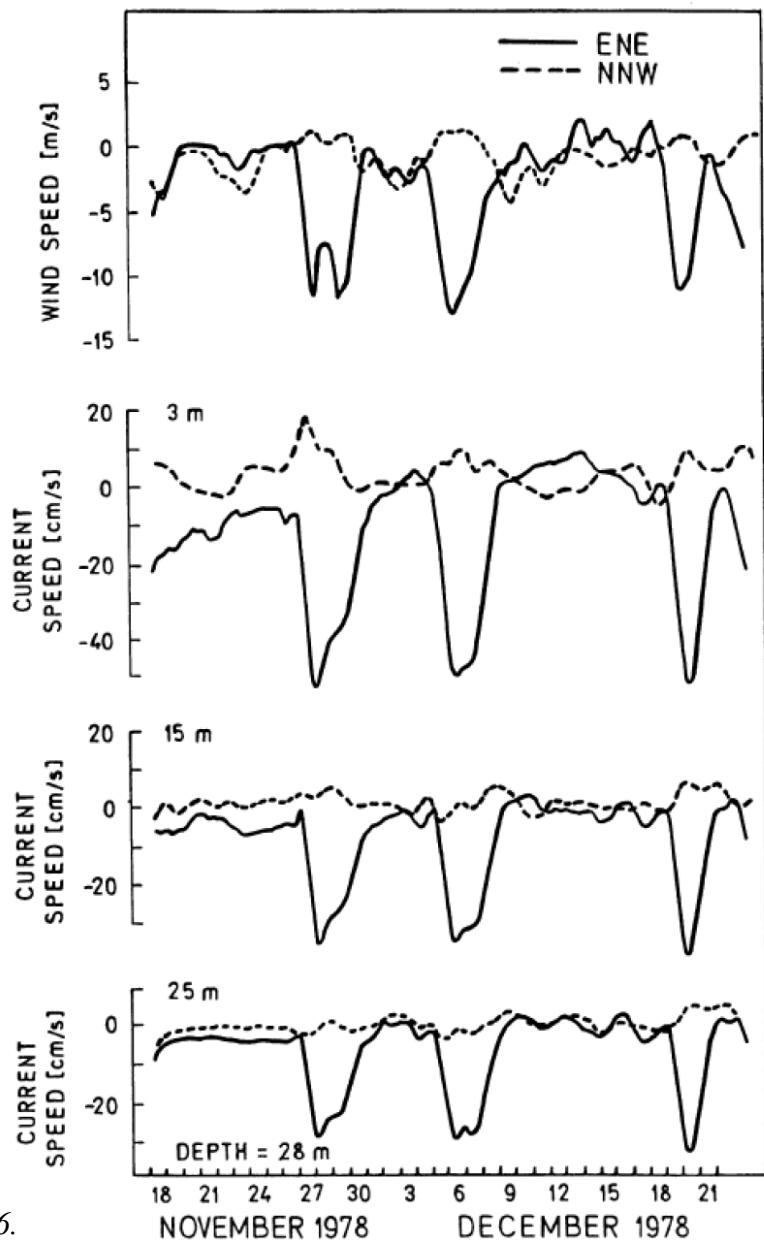
Zore, 1956.
Poulain, 2001.

Jadran – vjetrovno strujanje



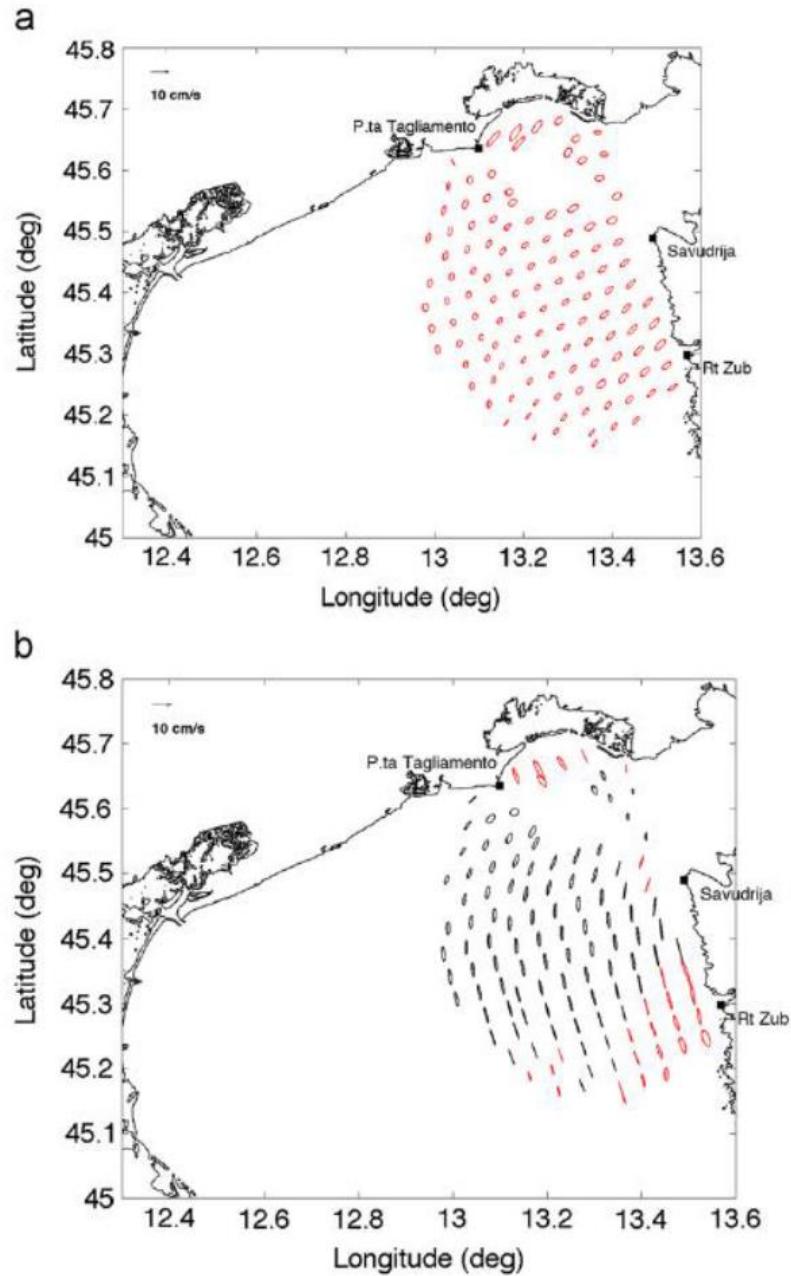
Jeffries, Lee, 2007.

Orlić et al., 1986.



Jadran – plimne struje

(a: K1, b: M2;
crveno: satna rotacija,
crno: protusatna rotacija)



2.2. Model nizozemske škole (M. P. H. Weenink, 1958, i dr.)

Početne jednadžbe

$$\frac{1}{\rho} \frac{\partial p}{\partial x} = fv + \frac{1}{\rho} \frac{\partial}{\partial z} \left(A \frac{\partial u}{\partial z} \right)$$

$$\frac{1}{\rho} \frac{\partial p}{\partial y} = -fu + \frac{1}{\rho} \frac{\partial}{\partial z} \left(A \frac{\partial v}{\partial z} \right)$$

$$\frac{1}{\rho} \frac{\partial p}{\partial z} = -g$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

Jednadžbe gibanja i kontinuiteta nakon integracije duž vertikale

$$g \frac{\partial \zeta}{\partial x} = \frac{f}{D} \mathbf{V} + \frac{1}{\rho} \left[\frac{\tau_x}{D} - \frac{\tau_{x,b}}{D} \right]$$

$$g \frac{\partial \zeta}{\partial y} = -\frac{f}{D} \mathbf{U} + \frac{1}{\rho} \left[\frac{\tau_y}{D} - \frac{\tau_{y,b}}{D} \right]$$

$$\frac{\partial \mathbf{U}}{\partial x} + \frac{\partial \mathbf{V}}{\partial y} = 0$$

Poprečnim deriviranjem dobiva se
(uz $f = \text{const.}$):

$$f \left[\frac{\partial D}{\partial x} \frac{\partial \Psi}{\partial y} - \frac{\partial D}{\partial y} \frac{\partial \Psi}{\partial x} \right] = \frac{D}{\rho} \left[\frac{\partial \tau_y}{\partial x} - \frac{\partial \tau_x}{\partial y} \right] - \frac{1}{\rho} \left[\frac{\partial D}{\partial x} \tau_y - \frac{\partial D}{\partial y} \tau_x \right] - \frac{D}{\rho} \left[\frac{\partial \tau_{y,b}}{\partial x} - \frac{\partial \tau_{x,b}}{\partial y} \right] + \frac{1}{\rho} \left[\frac{\partial D}{\partial x} \tau_{y,b} - \frac{\partial D}{\partial y} \tau_{x,b} \right]$$

gdje je:

$$\begin{aligned}\tau_{x,b} &= \rho r \frac{\mathbf{U}}{D} - n \tau_x \\ \tau_{y,b} &= \rho r \frac{\mathbf{V}}{D} - n \tau_y\end{aligned}$$

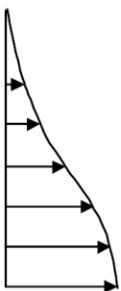
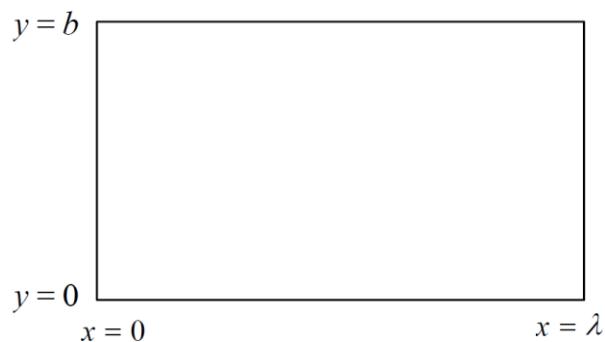
$$\mathbf{U} = -\frac{\partial \Psi}{\partial y}, \quad \mathbf{V} = \frac{\partial \Psi}{\partial x},$$

pa konačno rješavamo (uz $\Psi = 0$ duž obala):

$$f \left[\frac{\partial D}{\partial x} \frac{\partial \Psi}{\partial y} - \frac{\partial D}{\partial y} \frac{\partial \Psi}{\partial x} \right] + r \left[\frac{\partial^2 \Psi}{\partial x^2} + \frac{\partial^2 \Psi}{\partial y^2} \right] - \frac{2r}{D} \left[\frac{\partial D}{\partial x} \frac{\partial \Psi}{\partial x} + \frac{\partial D}{\partial y} \frac{\partial \Psi}{\partial y} \right] = \frac{D}{\rho} \left[\frac{\partial \tau_2}{\partial x} - \frac{\partial \tau_1}{\partial y} \right] - \frac{1}{\rho} \left[\frac{\partial D}{\partial x} \tau_2 - \frac{\partial D}{\partial y} \tau_1 \right]$$

$$\tau_1 = \tau_x + n \tau_x, \quad \tau_2 = \tau_y + n \tau_y.$$

Prvi slučaj: ravno dno (*struje rotora vjetra*)



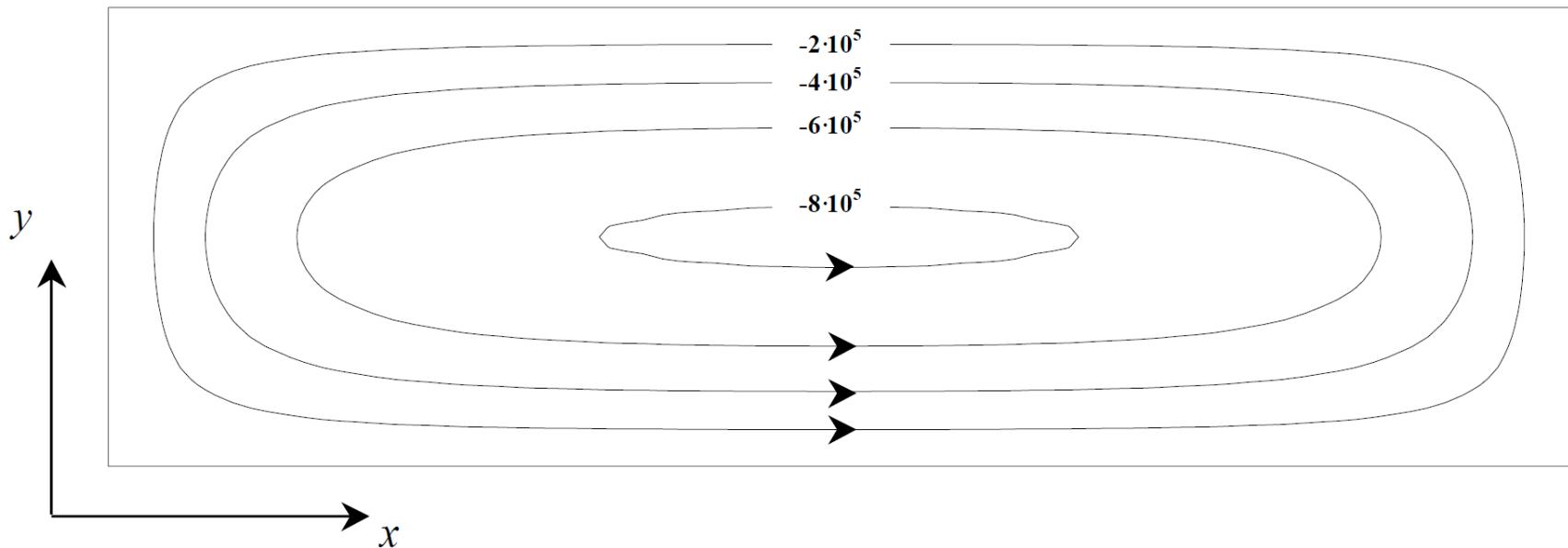
$$\tau_1 = F + F \cos \frac{\pi}{b} y$$

$$\frac{\partial^2 \Psi}{\partial x^2} + \frac{\partial^2 \Psi}{\partial y^2} = \alpha \sin \frac{\pi}{b} y$$

$$\alpha = \frac{D}{\rho r} \frac{F \pi}{b}$$

$$\Psi(x, y) = \alpha \frac{b^2}{\pi^2} \sin \frac{\pi}{b} y \left[e^{\frac{\pi}{b}(x-\lambda)} + e^{-\frac{\pi}{b}x} - 1 \right]$$

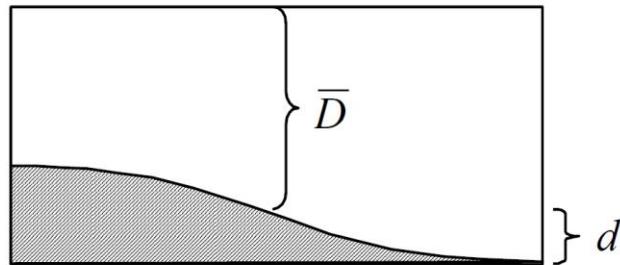
Struje rotora vjetra



Drugi slučaj: uniforman vjetar (struje nagiba dna)

x  \rightarrow y

$$\frac{\partial^2 \Psi}{\partial x^2} + \frac{\partial^2 \Psi}{\partial y^2} - \frac{f}{r} \frac{dD}{dy} \frac{\partial \Psi}{\partial x} - \frac{2}{D} \frac{dD}{dy} \frac{\partial \Psi}{\partial y} = \frac{1}{\rho r} \tau_1 \frac{dD}{dy}$$



$$D = \bar{D} - d \cos \frac{\pi}{b} y$$

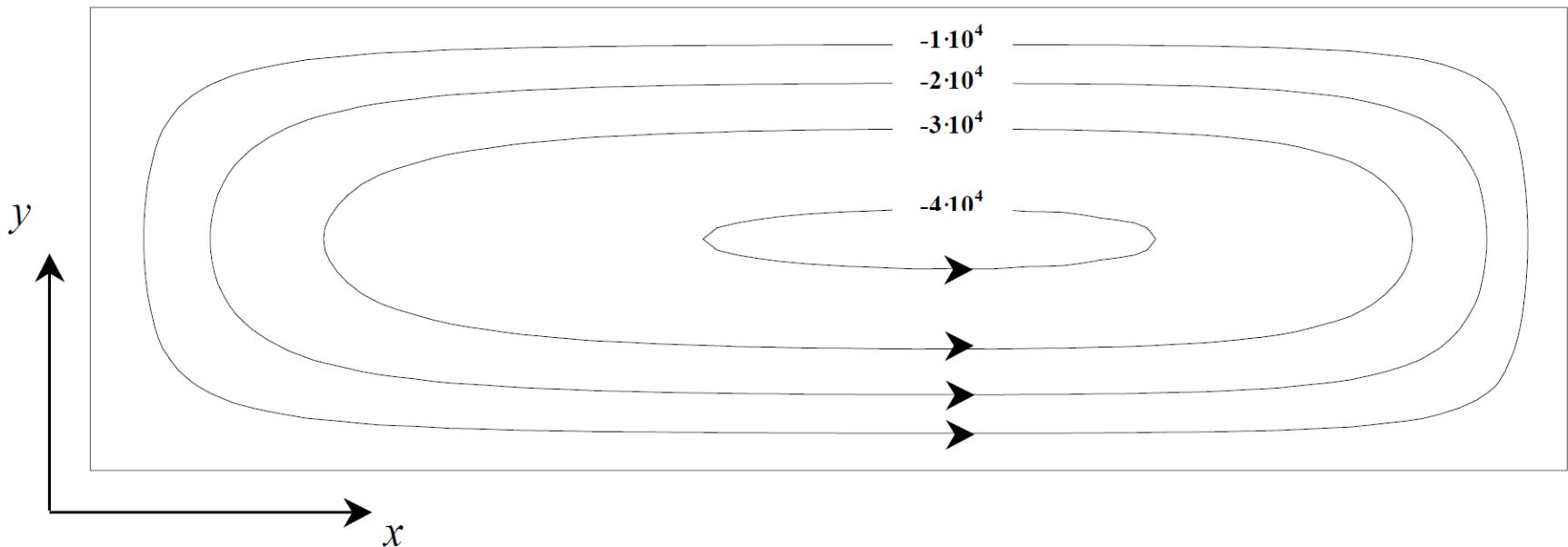
$$\frac{\partial^2 \Psi}{\partial x^2} + \frac{\partial^2 \Psi}{\partial y^2} + \alpha \frac{\partial \Psi}{\partial x} = \gamma \sin \frac{\pi}{b} y$$

$$\alpha = -\pi \frac{f}{r} \frac{d}{b}, \quad \gamma = \frac{\tau_1 d \pi}{r \rho b}$$

$$\Psi(x, y) = \gamma \frac{b^2}{\pi^2} \sin \frac{\pi}{b} y \left[\frac{(1 - e^{k_2 \lambda}) e^{k_1 x} + (e^{k_1 \lambda} - 1) e^{k_2 x}}{e^{k_1 \lambda} - e^{k_2 \lambda}} - 1 \right],$$

$$k_1 = -\frac{\alpha}{2} + \sqrt{\frac{\alpha^2}{4} + \frac{\pi^2}{b^2}}, \quad k_2 = -\frac{\alpha}{2} - \sqrt{\frac{\alpha^2}{4} + \frac{\pi^2}{b^2}}.$$

Struje nagiba dna



Treći slučaj: ravno dno i uniforman vjetar

$$\frac{\partial^2 \Psi}{\partial x^2} + \frac{\partial^2 \Psi}{\partial y^2} = 0$$

$$\Psi(0, y) = \Psi(\lambda, y) = \Psi(x, 0) = \Psi(x, b) = 0$$



$$\Psi = 0$$