

# Deveto predavanje (13. svibnja 2022.)

M. Orlić: Predavanja iz Dinamike obalnog mora

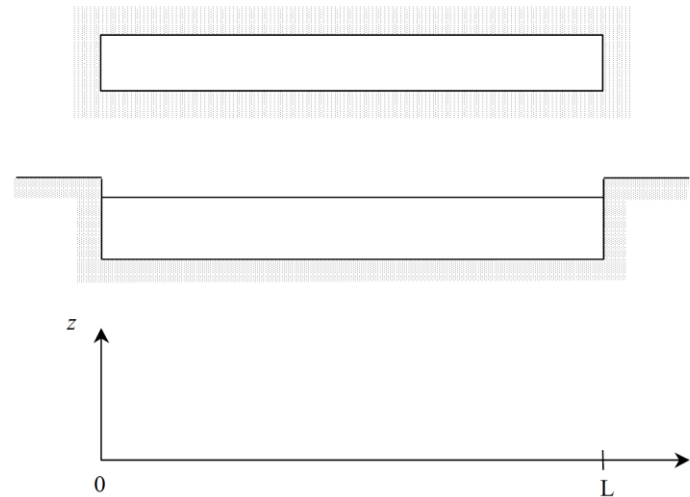
# Generiranje seša u uskom pravokutnom bazenu

## Polazne jednažbe

$$\frac{\partial U}{\partial t} = -g \frac{\partial \zeta}{\partial x} + \frac{1}{\rho D} [\tau_x - \tau_{xD}]$$

$$\frac{\partial V}{\partial t} = -g \frac{\partial \zeta}{\partial y} + \frac{1}{\rho D} [\tau_y - \tau_{yD}]$$

$$\frac{\partial(DU)}{\partial x} + \frac{\partial(DV)}{\partial y} + \frac{\partial \zeta}{\partial t} = 0$$



Zanemarujemo pridneno trenje,  
pretpostavljamo  $V = 0$  i  $D = \text{const.}$

# Situacija prije isključivanja vjetrova, uz postignuto stacionarno stanje

$$-\infty < t < 0$$

$$0 = -g \frac{\partial \zeta}{\partial x} + \frac{\tau_x}{\rho D}$$

$$\frac{\partial U}{\partial x} = 0.$$



$$\zeta = \frac{\tau_x}{g\rho D} \left( x - \frac{L}{2} \right),$$

$$U = 0.$$

# Situacija nakon isključivanja vjetra

$$0 \leq t < \infty$$

$$\frac{\partial U}{\partial t} = -g \frac{\partial \zeta}{\partial x}$$

$$D \frac{\partial U}{\partial x} + \frac{\partial \zeta}{\partial t} = 0.$$

$$\zeta(t = 0) = \frac{\tau_x}{g\rho D} \left( x - \frac{L}{2} \right),$$

$$U(t = 0) = 0, \quad \forall x,$$

$$U(x = 0, L) = 0, \quad \forall t.$$

# Rješavanje

$$\frac{\partial^2 \zeta}{\partial t^2} - gD \frac{\partial^2 \zeta}{\partial x^2} = 0$$

$$\zeta(t = 0) = \frac{\tau_x}{g\rho D} \left( x - \frac{L}{2} \right),$$

$$\frac{\partial \zeta}{\partial t}(t = 0) = 0, \quad \forall x,$$

$$\frac{\partial \zeta}{\partial x}(x = 0, L) = 0, \quad \forall t.$$

# Rješenje (1)

$$\zeta = \sum_{n=1}^{\infty} A_n \cos \frac{n\pi}{L} x \cos \sigma_n t$$

$$\sigma_n = \frac{n\pi}{L} \sqrt{gD}, \quad n = 1, 2, 3, \dots$$

$$\sum_{n=1}^{\infty} A_n \cos \frac{n\pi}{L} x = \frac{\tau_x}{g\rho D} \left( x - \frac{L}{2} \right)$$

## Rješenje (2)

$$\zeta = \frac{\tau_x}{g\rho D} \frac{4L}{\pi^2} \left( -\cos \frac{\pi}{L} x \cos \sigma_1 t - \frac{1}{9} \cos \frac{3\pi}{L} x \cos \sigma_3 t - \dots \right)$$

$$U = -\frac{\tau_x}{g\rho D^2} \frac{4L^2}{\pi^3} \left( \sigma_1 \sin \frac{\pi}{L} x \sin \sigma_1 t + \frac{\sigma_3}{27} \sin \frac{3\pi}{L} x \sin \sigma_3 t + \dots \right)$$