

# 1 Gustoća stanja

## 1.1 Sedlena točka u TB modelu

Energija u TB modelu:

$$E(\vec{k}) = -2t(\cos(kx_a) + \cos(k_y a) + \cos(k_z a))$$

Sedlena točka je oko energije  $E = -2t$ . Postoji 6 točaka u Brillouinovoj zoni koje odgovaraju sedlenoj točki. Usredotočiti ćemo se samo na jednu od njih:

$$\begin{aligned} |k_x| &\ll \frac{\pi}{a} \\ |k_y| &\ll \frac{\pi}{a} \\ k_z &\approx \pi - \delta k_z, \quad \delta k_z \ll \frac{\pi}{a} \end{aligned}$$

Tada je:

$$E(\vec{k}) \approx -2t + ta^2(k_x^2 + k_y^2) - ta^2\delta k_z^2$$

Doprinos te točke gustoći stanja:

$$\begin{aligned} \delta g(E) &= 2 \frac{V}{(2\pi)^3} \int dk_x dk_y dk_z \delta(E + 2t - ta^2(k_x^2 + k_y^2) + ta^2\delta k_z^2) \\ &= 2 \frac{V}{(2\pi)^3 ta^3} \int dx dy dz \delta(\epsilon - x^2 - y^2 + z^2) \end{aligned}$$

gdje je

$$\epsilon = \frac{E + 2t}{t}$$

$\epsilon$  može biti pozitivno i negativno. To su dvije situacije koje se trebaju posebno razmotriti. Područje integracije po valnim brojevima treba ograničiti da bude u blizini sedlenih točaka u Brillouinovoj zoni. To se može postići, npr. s ovim ograničenjem:

$$x^2 + y^2 + z^2 < 1$$

To znači da se integrira po valnim brojevima unutar sfere radijusa 1 oko sedlene točke. Uvođenje polarnih koordinata:

$$\begin{aligned} x &= \rho \cos \phi \\ y &= \rho \sin \phi \end{aligned}$$

dobivamo:

$$\delta g(E) = 2 \frac{V}{(2\pi)^2 ta^3} \int d\rho dz \rho \delta(\epsilon - \rho^2 + z^2)$$

Nadalje može se uvesti slijedeća smjena varijabli:

$$\begin{aligned}\rho &= r \cosh \alpha \\ z &= r \sinh \alpha\end{aligned}$$

ako je  $\epsilon > 0$ , odnosno:

$$\begin{aligned}\rho &= r \sinh \alpha \\ z &= r \cosh \alpha\end{aligned}$$

ako je  $\epsilon < 0$ . To implicira da je:

$$r^2(\cosh^2 \alpha + \sinh^2 \alpha) = r^2 \cosh 2\alpha < 1$$

Gornja granica područja integracije po varijabli  $\alpha$ :

$$\begin{aligned}r^2 \cosh 2\alpha_{max} &= 1 \quad \Rightarrow \\ \alpha_{max} &= 0.5 \operatorname{arch}\left(\frac{1}{r^2}\right) \\ &= 0.5 \ln\left(\frac{1}{r^2} + \sqrt{\frac{1}{r^4} - 1}\right) \approx 0.5 \ln \frac{2}{r^2} = \ln \frac{\sqrt{2}}{r}\end{aligned}$$

Očekujemo da je  $r^2$  malo, reda veličine  $\epsilon$ . U slučaju kada je  $\epsilon > 0$ :

$$\begin{aligned}\delta g(E) &= 2 \frac{V}{(2\pi)^2 t a^3} \int dr d\alpha r r \cosh \alpha \delta(\epsilon - r^2) \\ &= 2 \frac{V}{(2\pi)^2 t a^3} \int dr r^2 \delta(\epsilon - r^2) \int_0^{\alpha_{max}} d\alpha \cosh \alpha = 2 \frac{V}{(2\pi)^2 t a^3} \int dr r^2 \delta(\epsilon - r^2) \underbrace{\sinh \alpha_{max}}_{\approx 0.5 \frac{\sqrt{2}}{r}} \\ &= \frac{V}{(2\pi)^2 t a^3} \int dr r^2 \delta(\epsilon - r^2) \frac{\sqrt{2}}{r} = \frac{V}{\sqrt{2}(2\pi)^2 t a^3} = \text{konst.}\end{aligned}$$

ako je  $\epsilon < 0$ :

$$\begin{aligned}\delta g(E) &= 2 \frac{V}{(2\pi)^2 t a^3} \int dr d\alpha r r \sinh \alpha \delta(-|\epsilon| + r^2) \\ &= 2 \frac{V}{(2\pi)^2 t a^3} \int dr r^2 \delta(r^2 - |\epsilon|) \int_0^{\alpha_{max}} d\alpha \sinh \alpha \\ &= 2 \frac{V}{(2\pi)^2 t a^3} \int dr r^2 \delta(r^2 - |\epsilon|) \left( \underbrace{\cosh \alpha_{max}}_{\approx 0.5 \frac{\sqrt{2}}{r}} - 1.0 \right) \\ &= \frac{V}{\sqrt{2}(2\pi)^2 t a^3} \int de (1 - \sqrt{2e}) \delta(e - \epsilon) \\ &= \frac{V}{\sqrt{2}(2\pi)^2 t a^3} (1 - \sqrt{2|\epsilon|})\end{aligned}$$

## 2 Gustoća stanja 2d TB modelu

Energija u TB modelu:

$$\begin{aligned}
 E(\vec{k}) &= -2t [\cos(k_x a) + \cos(k_y a)] \\
 &= -4t + 2t [1 - \cos(k_x a) + 1 - \cos(k_y a)] \\
 &= -4t + 4t \left[ \sin^2 \left( \frac{k_x a}{2} \right) + \sin^2 \left( \frac{k_y a}{2} \right) \right]
 \end{aligned}$$

Uvodimo nove varijable  $r$  i  $\phi$ :

$$\begin{aligned}
 \sin \left( \frac{k_x a}{2} \right) &= r \cos \left( \frac{\phi}{2} \right) & \Rightarrow & \quad k_x = \frac{2}{a} \arcsin \left( r \cos \left( \frac{\phi}{2} \right) \right) \\
 \sin \left( \frac{k_y a}{2} \right) &= r \sin \left( \frac{\phi}{2} \right) & \Rightarrow & \quad k_y = \frac{2}{a} \arcsin \left( r \sin \left( \frac{\phi}{2} \right) \right)
 \end{aligned}$$

Jakobijan:

$$\begin{aligned}
 \left| \frac{\partial(k_x, k_y)}{\partial(r, \phi)} \right| &= \left| \begin{array}{cc} \frac{2 \cos \left( \frac{\phi}{2} \right)}{a \sqrt{1 - r^2 \cos^2 \left( \frac{\phi}{2} \right)}} & - \frac{r \sin \left( \frac{\phi}{2} \right)}{a \sqrt{1 - r^2 \cos^2 \left( \frac{\phi}{2} \right)}} \\ \frac{2 \sin \left( \frac{\phi}{2} \right)}{a \sqrt{1 - r^2 \sin^2 \left( \frac{\phi}{2} \right)}} & \frac{r \cos \left( \frac{\phi}{2} \right)}{a \sqrt{1 - r^2 \sin^2 \left( \frac{\phi}{2} \right)}} \end{array} \right| \\
 &= \frac{2r}{a^2 \sqrt{1 - r^2 \cos^2 \left( \frac{\phi}{2} \right)} \sqrt{1 - r^2 \sin^2 \left( \frac{\phi}{2} \right)}} = \frac{2r}{a^2 \sqrt{1 - r^2 + r^4 \cos^2 \left( \frac{\phi}{2} \right) \sin^2 \left( \frac{\phi}{2} \right)}} \\
 &= \frac{2r}{a^2 \sqrt{1 - r^2 + 0.25r^4 \sin^2 \phi}} = \frac{2r}{a^2 \sqrt{(1 - r^2 + 0.25r^4) - 0.25r^4 \cos^2 \phi}} \\
 &= \frac{2r}{a^2 \sqrt{1 - r^2 + 0.25r^4}} \frac{1}{\sqrt{1 - k^2 \sin^2 \left( \frac{\pi}{2} - \phi \right)}}
 \end{aligned}$$

gdje je:

$$k = \frac{0.5r^2}{\sqrt{1 - r^2 + 0.25r^4}}$$

Gustoća stanja:

$$\begin{aligned}
g(E) &= \frac{2}{(2\pi)^2} \int dk_x dk_y \delta(E + 2t [\cos(k_x a) + \cos(k_y a)]) \\
&= \frac{2 \cdot 4}{(2\pi)^2} \int_0^\pi dk_x \int_0^\pi dk_y \delta(E + 4t - 4tr^2) = \frac{2}{\pi^2} \int_0^1 dr \int_0^\pi d\phi \left| \frac{\partial(k_x, k_y)}{\partial(r, \phi)} \right| \delta(E + 4t - 4tr^2) \\
&= \frac{2}{\pi^2} \int_0^1 dr \int_0^\pi d\phi \delta(E + 4t - 4tr^2) \frac{2r}{a^2 \sqrt{1 - r^2 + 0.25r^4}} \frac{1}{\sqrt{1 - k^2 \sin^2(\frac{\pi}{2} - \phi)}} \\
&= \frac{4}{\pi^2} \int_0^1 dr \delta(E + 4t - 4tr^2) \frac{2r}{a^2 \sqrt{1 - r^2 + 0.25r^4}} \int_0^{0.5\pi} d\phi' \frac{1}{\sqrt{1 - k^2 \sin^2 \phi'}} \\
&= \frac{4}{\pi^2} \int_0^1 dr \delta(E + 4t - 4tr^2) \frac{2r}{a^2 \sqrt{1 - r^2 + 0.25r^4}} F(k) \\
&= \frac{1}{(a\pi)^2 t} \frac{F(k_E)}{\sqrt{1 - r_E^2 + 0.25r_E^4}}
\end{aligned}$$

gdje je:

$$\begin{aligned}
r_E &= \sqrt{1 - \frac{|E|}{4t}} \\
k_E &= \frac{0.5r_E^2}{\sqrt{1 - r_E^2 + 0.25r_E^4}}
\end{aligned}$$